

61.27

PCD1.A1000-A20

E-Line S-Serie RIO 10DO

The S-Serie E-Line RIO modules are controlled via the RS-485 serial communication protocols S-Bus and Modbus for decentralised automation using industrial quality components. The data point mix is specifically designed for building automation applications.



The compact design according to DIN 43880 enables installation in electrical distribution boxes even in the most confined spaces. Installation and maintenance are facilitated by the local manual override for each output. Remote maintenance is also possible by accessing the manual override using the Saia PCD® controller's web interface. Programming is very efficient and fast using a complete FBox library with web templates for S-Bus. Individual programs may directly access the data points via Registers and Flags. Complete documentation is included in this data sheet.

Features

- ► S-Bus protocol optimized for fast data exchange
- ► Modbus protocol for integration in multi-vendor installations*
- ► Local override operating level via web panel or buttons on the module
- ► Easy programming using the FBox library and web templates
- ▶ Industrial hardware in accordance with IEC EN 61131-2
- ► Pluggable terminal blocks
- ▶ Bridge connectors for power supply and communication
- ▶ Bus termination on board
- ► Configurable Bi-Colour LEDs and labelling for I/Os

General technical data

Power supply

| Supply voltage | 24 VDC, –15/+20% max. incl. 5% ripple (in accordance with EN/IEC 61131-2) |
|---------------------|--|
| Power consumption | 1.2 3 W |
| Power supply bridge | 24 VDC, 5 A max., up to 40 modules |

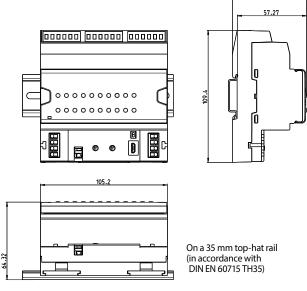
Interfaces

| Communications interface | RS-485 Baud rate: 9,600, 19,200, 38,400, 57,600, 115,200 bps (Autobauding) Micro USB, Type B | | |
|--------------------------|---|--|--|
| Address switch | Two rotary switches 0 9 Address range 0 98 | | |
| Bus termination | Integrated switch to activate and inactivate resistor termination | | |

General data

| Ambient temperature | Operation: 0 +55 °C Storage: −40 +70 °C | |
|---------------------|---|--|
| Protection class | IP 20 | |
| Package | Single carton package with 1 Module incl. terminal blocks, 1 bridge connector | |

Dimensions and installation



Housing width 6 HP (105 mm) Compatible with electrical control cabinet (in accordance with DIN 43880, size 2×55 mm)

^{*} By default the module is working in S-Bus Data Mode with Autobaud detection. To configure Modbus the Windows-based application "E-LineApp" is required

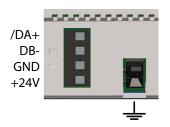
Terminal technology

Push-in spring terminals enable wiring with rigid or flexible wires with a diameter up to 1.5 mm². A max. of 1 mm² is permitted with cable end sleeves.



Connection concept

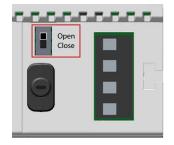
For easy installation the power supply and communication bus is available together at one connector. The push-in spring terminals enable wiring as well support the connector bridge.





Bus termination

The module provides an active bus termination. It is switched off by factory default. To enable the termination, the switch need to be in the "Close" position.



Status LED

OFF No Power

Green Communication OK
Green blink Auto bauding in progress
Orange No communication

Red Error

Red/Green alternate Booter mode

(e.g. during Firmware download)

Red blink Internal fatal error



Service interface

The USB interface provides access to the communication protocol configuration. Firmware updates can also be downloaded via Saia PG5® Firmware Download tool.



Reset button

Pushed over 20 seconds: The button needs to be pushed for minimum 20 seconds and released during the first minute after power up. All user settings are reset to factory default values.

Pushed at power up: Power off the device and press the button. Power on and release the button before 5 seconds have passed. The device stays in boot mode for further actions like firmware download etc.

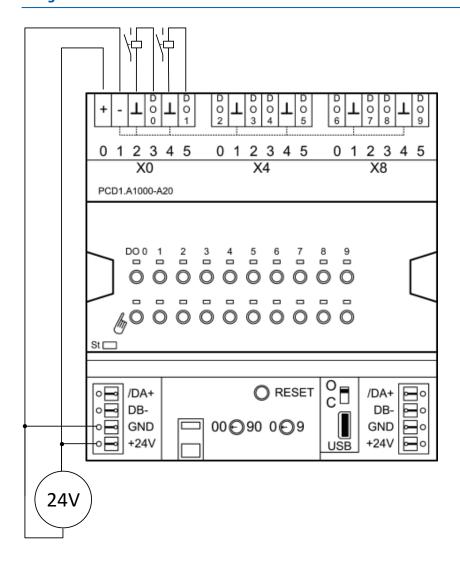


Output configuration

Digital outputs

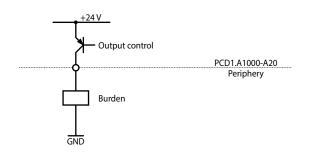
| Number | 10, electrically connected | |
|--------------------------|--|--|
| Voltage range | 10 32 VDC, smoothed, max. 10 % residual ripple | |
| Voltage drop | ax. 0.3 V at 500 mA | |
| Output current | 5 500 mA (leakage current max. 0,1 mA). Within the voltage range 10 24 VDC, the load resistance should be at least 48 Ω | |
| Short circuit protection | yes | |
| Operating mode | source operation (positive switching) | |
| Output delay | depending on the data communication cycle, typically 50 ms per module @115k Baud | |
| Manual operation | local override operation by buttons | |

Assignment overview

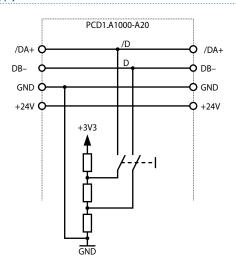


Connection diagrams

Digital output



Power supply and bus termination



LED Signalisation

Status LED

OFF No Power

Green Communication OK
Green blink Auto bauding in progress
Orange No communication

Red Error

Red/Green alternate Booter mode

(e.g. during Firmware download)

Red blink Internal fatal error

Digital output

The Output indication LED can be configured in colour and blink code separately for output state Low and High.

LED colour

- ▶ Off
- ► Red
- ► Green*
- ► Orange (red + green)

LED blink code

- ► No blink*
- ► Slow blinking (0.5 flashes per second)
- ► Fast blinking (2 flashes per second)

Manual mode

The Manual override LED is Off in automatic mode and orange in case of manual override is active.

LED colour

- ► Off (automatic)
- ► Orange manual mode active

LED blink code

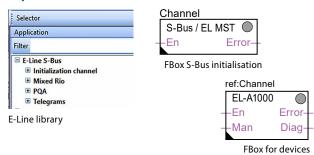
- ► No blink (local manual override)
- ▶ Blinking 1 flash per second (remote manual override)

^{*}Factory default



The modules are addressed and programmed with Saia PG5® Fupla FBoxes. Web templates are available for the operation and visualisation of the manual override function.

Fupla



Communication FBox

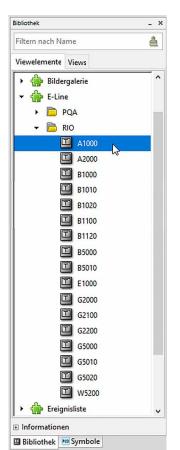
- ▶ Data exchange for I/O via optimised S-Bus
- ► Configurable save state for bus interruption or timeout
- ▶ Direct generation of the symbols
- ▶ Reading and writing of the status of the manual override status
- ► Direct compatibility with web macros



Further information, including which FBoxes are supported, Getting Started, etc., can be found on our support page www.sbc-support.com.

Web templates

Web templates are available for the operation and visualisation of the manual override function.







By using the local override function, commissioning can take place independently of the master station.

In addition, the manual operation can also be controlled remotely using a touch panel. If the bus line is cut off, the module keeps the manually set values. Traditional manual operation in the control cabinet door via potentiometers and switches can therefore be completely replaced by this solution.

Five operating modes can be selected for the manual operating function:

| Operat- | Description | Operation | | |
|--------------|--|-----------|----------------------------------|--|
| ing modes | - | | via remote communica- tion | |
| 1 | Manual operation deactivated | × | × | |
| 2 | Operation permitted from the module only | ✓ | × | |
| 3 | Operation permitted from the module and limited operation from the panel. If manual operation is activated at the module, it cannot be reset from the panel. | ✓ | (condi- tional) | |
| 4 | Unlimited operation from the panel and module | ✓ | ✓ | |
| 5 | Panel operation (remote) | × | ✓ | |



Depending on the application, reset of manually set values is allowed from a panel. To address this requirement, it is possible to deactivate or limit manual operation function.

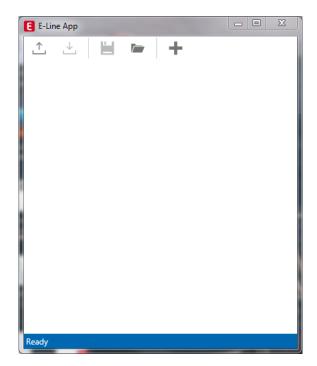


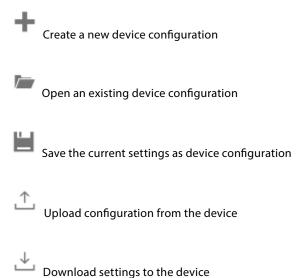
The inputs of the E-Line RIO modules can be addressed via the standard S-Bus. However the FBox from the E-Line library is used for the configuration of these modules.

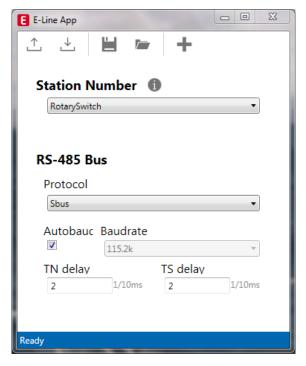
It is therefore recommended to use the optimised S-Bus protocol and the corresponding FBoxes from the E-Line library. Mixed mode operation is not recommended.

E-line App device setup

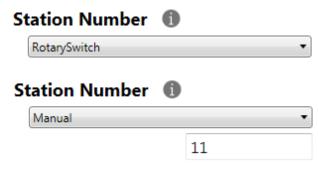
E-Line RIOs support the device setup by a windows application program connected via USB. The installer is available for download from the SBC support page: www.sbc-support.com → E-Line RIO IO Modules.







The station number can be set by the rotary switches at the device in the range of $0 \dots 98$. If the rotary switches are set to position 99 the station number can be defined by the device configuration in a range of $0 \dots 253$.



The serial communication protocol can be defined either as S-Bus or Modbus. By default the modules are delivered from factory with S-Bus.

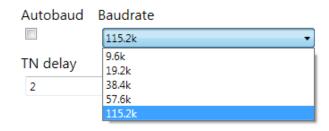
RS-485 Bus

Protocol

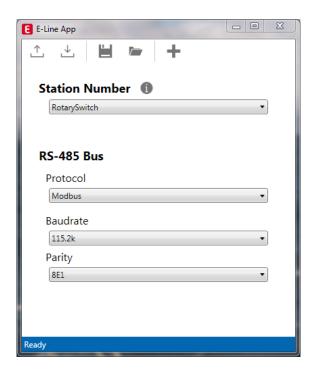


The Baudrate can be defined as automatic detection (default) or set to a specific value. The drop down choice will be available when the check box "Automatic" is unchecked. TN delay and TS delay shall be left at their default values of 2.

S-Bus settings

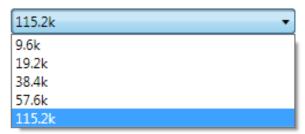


Modbus settings



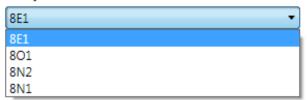
The Baudrate is set by default to 115 k. It can be defined as choice of the list.

Baudrate



For best interoperability, the Parity Mode and number of Stop Bits can also be set.

Parity



S-Bus communication

S-Bus communication is based on Saia PCD® S-Bus Data Mode. Only the set-up of a unique S-Bus address within the communication line is required to establish a communication between Saia PCD® controllers and E-Line RIO modules. The address can be set using the rotary switches at the front of the module. The baud rate will be learned from the network by factory default. In addition a Windows-based application is available for manual parameter setup. Configuration parameters as well as manual override state and value are saved non-volatile. A delay of about one second between a manual state change and non-volatile saving has to be taken into consideration.

Device address

▶ 0...98 Address is taken from the rotary switches

▶ 99 Address is taken from the device configuration. The address is settable with the E-Line configuration software.

Start-up procedure

► Reboot: All outputs are cleared (Off state)

► <1 sec. Output in manual operation are set according to the state before power down.

▶ Outputs in automatic mode

If, after reboot, no telegram is received within the "safe state power-on timeout," the module enters into the safe state mode and sets the outputs according to their configured values.

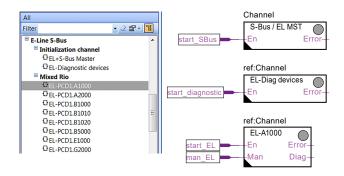
On reception of a valid command telegram the outputs are controlled by the communication. When no communication update follows within the "safe state com. timeout" the module enters into safe state and sets the outputs according to their configured values.

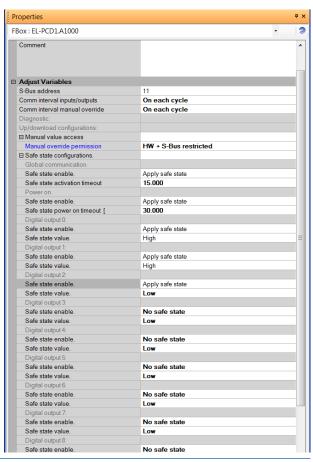
Usage of the E-Line module-specific FBoxes

The usage of the E-Line module-specific FBoxes from the E-Line S-Bus Fupla library allows an easy and efficient commissioning of the E-Line RIO.

The FBox allows the definition and configuration of all possible functionalities of the E-Line RIO like manual override permission, usage of safe state mode, behaviour and colour of the LED's and so on.

In the background, the FBox uses the fast 'E-Line S-Bus' protocol for a high speed communication between the master and the RIO.





Direct access to the RIO media with standard S-Bus send and receive telegrams

The following chapter describes the media and parameter mapping to Registers and Flags for individual programming. For efficient PCD programming the E-Line RIO FBox family and templates are suitable for most applications. Only individual programming (e.g. Instruction List) requires standard S-Bus communication.

Digital outputs

| Output | Output Value | Read/Write | Manual override Read/Write* Communication | | Manual override Local | Read/Write** |
|------------------|--------------|------------|---|----|--------------------------|--------------|
| Digital Output 0 | Flag 30 | RW | Register 90 | RW | Register 100 | R |
| Digital Output 1 | Flag 31 | RW | Register 91 | RW | Register 101 | R |
| Digital Output 2 | Flag 32 | RW | Register 92 | RW | Register 102 | R |
| Digital Output 3 | Flag 33 | RW | Register 93 | RW | Register 103 | R |
| Digital Output 4 | Flag 34 | RW | Register 94 | RW | Register 104 | R |
| Digital Output 5 | Flag 35 | RW | Register 95 | RW | Register 105 | R |
| Digital Output 6 | Flag 36 | RW | Register 96 | RW | Register 106 | R |
| Digital Output 7 | Flag 37 | RW | Register 97 | RW | Register 107 | R |
| Digital Output 8 | Flag 38 | RW | Register 98 | RW | Register 108 | R |
| Digital Output 9 | Flag 39 | RW | Register 99 | RW | Register 109 | R |

^{*} Writable only if S-Bus permission is set in the configuration, otherwise write has no effect

Normal operation: The outputs are set according the flag set by the communication.

Manual operation: The output are set according to the manual command, the communication flags are ignored.

Safe State: In case of a broken communication, a safe state value can be applied, see table Safe State Configuration.

Register format for manual override via S-Bus (Reg. 90 ... 99):

Bit 0 Current output value

Bit 30 1: output is driven in manual override by S-Bus

Bit 31 1: output is driven in manual override by local push buttons

Register format for local manual override (Reg. 100 ... 109):

Bit 0 Current output value

Bit 31 1: output is driven in manual override by local push buttons

LED Configuration

| Digital Output 0 | Register 300 | RW |
|------------------|--------------|----|
| Digital Output 1 | Register 301 | RW |
| Digital Output 2 | Register 302 | RW |
| Digital Output 3 | Register 303 | RW |
| Digital Output 4 | Register 304 | RW |
| Digital Output 5 | Register 305 | RW |
| Digital Output 6 | Register 306 | RW |
| Digital Output 7 | Register 307 | RW |
| Digital Output 8 | Register 308 | RW |
| Digital Output 9 | Register 309 | RW |

| oaic | tor | for | ma | +. |
|-------|-----|-----|----|-----|
| Regis | ter | 101 | ma | ıt: |

| Bit 0 7 | I/O state Low | LED colour |
|-----------|----------------|----------------|
| Bit 8 15 | I/O state Low | LED blink code |
| Bit 16 23 | I/O state High | LED colour |
| Bit 24 31 | I/O state High | LED blink code |

LED colour 0: Off 1: Red

2: Green

3: Orange (red + green)

LED blink code 0: No blink

1: Slow blinking (0.5 flashes per second)

2: Fast blinking (2 flashes per second)

Factory default: Low: off, High: LED colour 2 (green), no blink

The LEDs can be configured individually depending on the I/O state in colour and blink code.

^{**} Writing to these registers has no effect. Used only if hardware permission is set in the configuration

Configuration for safe state and manual override

| Output | Safe State Enable | Read/Write | Safe State Value | Read/Write |
|--|---|------------|------------------|------------|
| Digital Output 0 | Flag 320 | RW | Flag 350 | RW |
| Digital Output 1 | Flag 321 | RW | Flag 351 | RW |
| Digital Output 2 | Flag 322 | RW | Flag 352 | RW |
| Digital Output 3 | Flag 323 | RW | Flag 353 | RW |
| Digital Output 4 | Flag 324 | RW | Flag 354 | RW |
| Digital Output 5 | Flag 325 | RW | Flag 355 | RW |
| Digital Output 6 | Flag 326 | RW | Flag 356 | RW |
| Digital Output 7 | Flag 327 | RW | Flag 357 | RW |
| Digital Output 8 | Flag 328 | RW | Flag 358 | RW |
| Digital Output 9 | Flag 329 | RW | Flag 359 | RW |
| | | | | |
| Communication safe state enabl | e default 0 (disabled) | | Flag 400 | RW |
| Power-On safe state enable defa | ult 0 (disabled) | | Flag 401 | RW |
| Power-On safe state timeout [ms Valid values 1000 100,000,000 | | | Register 590 | RW |
| Communication safe state timeo Valid values 1000 100,000,000 | | | Register 591 | RW |
| Manual operation mode Bit 0: Disabled Bit 1: Remote control li Bit 2: Local operation e Bit 3: Remote control u Bits can be combined to enable | nabled, default 1 nlimited*, default 0 | | Register 592 | RW |

^{*}If manual operation is locally activated at the module, the output value and manual state cannot be set/reset remotely

Manual operation mode:

- ▶ Disabled (0)
- ► Local operation only (4, Bit 2 set)
- ▶ Local operation enabled, remote limited (6, Bit 1 and 2 set), default
- ▶ Local and remote operation enabled (12, Bit 2 and 3 set)
- ► Remote operation only, local operation disabled (8, Bit 3 set)

The safe state enable flag and the safe state value are combined in the following way:

- Setting the enable flag to 0 keep the output value unchanged in case of safe state occurrence.
- Setting the enable flag to 1 writes the safe state value in case of safe state occurrence.

Device Information

| Firmware version (Decimal xyyzz, 10802 → 1.08.02) | Register 600 | R |
|--|------------------|---|
| Number of supported registers | Register 601 | R |
| Number of supported flags | Register 602 | R |
| Product type (ASCII String)*** | Register 605 608 | R |
| Hardware version (Hex) | Register 609 | R |
| Serial number (Hex) | Register 611 612 | R |
| Communication protocol (1:S-Bus Slave, 3:Modbus) | Register 620 | R |
| Communication baud rate | Register 621 | R |
| Communication auto baud enable (0:disabled, 1:enabled) | Register 622 | R |
| Communication TN delay * | Register 623 | R |
| Communication TS delay ** | Register 624 | R |
| Communication module address | Register 626 | R |

^{*} Time in 0.1 ms (e.g. 2 means 200 us) before setting activation of RS-485 line driver send mode (only used for S-Bus slave protocol)

** Time in 0.1 ms (e.g. 2 means 200 us) before sending the first character after line driver activation (only used for S-Bus slave protocol)

** The four registers contain the ASCII characters of the product type.

E.g. for PCD1.A2000-A20:

0605: 50434431H 0606: 2E413230H 0607: 30302D41H 0608: 32300000H

Modbus communication

Modbus fulfils the requirements for standard communication protocols. It is based on Modbus RTU. The Windows-based configuration software is required to enable and set up the Modbus communication parameters. The device address can be set up with the rotary switches at the front of the module. Configuration parameters as well as manual override state and value are saved non-volatile. A delay of about one second between a manual state change and non-volatile saving has to be taken into consideration.

Device address

▶ 0...98 Address is taken from the rotary switches

▶ 99 Address is taken from the device configuration. The address is settable with the E-Line configuration

Start-up procedure

► Reboot: All outputs are cleared (Off state)

► <1 sec. Output in manual operation are set according to the state before power down.

▶ Outputs in automatic mode

If, after reboot, no telegram is received within the "safe state power-on timeout," the module enters into the safe state mode and sets the outputs according to their configured values.

On reception of a valid command telegram the outputs are controlled by the communication. When no communication update follows within the "safe state com. timeout" the module enters into safe state and sets the outputs according to their configured values.

The following chapter describes the media and parameter mapping to Registers and Flags (=Coils).

Supported Modbus services:

- ► Function code 1 (read coil output)
- ► Function code 3 (read registers)
- ► Function code 15 (write multiple coils outputs)
- ► Function code 16 (write multiple registers)

Read coils

| Request | | | | | | | |
|--|---|-----------|----------|-----------|----------|-----------|----------|
| Address Function Start Address Number of coils to read CRC | | | | RC | | | |
| 0254 | 1 | High-Byte | Low-Byte | High-Byte | Low-Byte | High-Byte | Low-Byte |

| Reply | | | | | | | | | |
|---------|----------|-------------|----------|-----------|-----|-----------|----------|--|--|
| Address | Function | No. of Byte | | Data | | | CRC | | |
| 0 254 | 1 | 0 256 | Coil 0 7 | Coil 8 15 | ••• | High-Byte | Low-Byte | | |

Write coils

| Request | Request | | | | | | | | | |
|---------|--------------------------------|-----------|--------------------------|-----------|-----------|--------------|----------|-----|-----------|----------|
| Address | Address Function Start Address | | Number of Coils to write | | Coil data | | | CRC | | |
| 0254 | 15 | High-Byte | Low-Byte | High-Byte | Low-Byte | No. of Bytes | Coil 0 7 | | High-Byte | Low-Byte |

| Reply | Reply | | | | | | | | |
|------------------|-------|---------------|----------|-------------------------|----------|-----------|----------|--|--|
| Address Function | | Start Address | | Number of written Coils | | CRC | | | |
| 0254 | 15 | High-Byte | Low-Byte | High-Byte | Low-Byte | High-Byte | Low-Byte | | |

Read register

| Request | Request | | | | | | | |
|---------|----------------------------|-----------|-------------|--------------|----------|-----------|----------|--|
| Address | ess Function Start Address | | No. of Regi | ster to read | CRC | | | |
| 0254 | 3 | High-Byte | Low-Byte | High-Byte | Low-Byte | High-Byte | Low-Byte | |

| Reply | Reply | | | | | | | | |
|---------|----------------------|-------|--------------|-------------------------|--|-----------|----------|--|--|
| Address | Function No. of Byte | | Register Sta | Register Start Addr + 0 | | CF | RC | | |
| 0254 | 3 | 0 256 | High-Byte | Low-Byte | | High-Byte | Low-Byte | | |

Write register

| Request | equest | | | | | | | | | | |
|------------------|--------|-----------|------------------------------|-----------|--|-------|----------|-----------|-----|-----------|----------|
| Address Function | | Start A | art Address No. of Registers | | No. of Bytes Data Word: Start Addr + 0 | | | Addr + n | CRC | | |
| 0254 | 16 | High-Byte | Low-Byte | High-Byte | Low-Byte | 2 256 | Low-Byte | High-Byte | ••• | High-Byte | Low-Byte |

| | Reply | | | | | | | | |
|------------------|-------|---------|-----------|--------------|-------------|----------|-----------|----------|--|
| Address Function | | Start A | ddress | No of writte | n Registers | CF | RC | | |
| Ī | 0254 | 16 | High-Byte | Low-Byte | High-Byte | Low-Byte | High-Byte | Low-Byte | |

The CRC has to be calculated over all telegram bytes starting with address field up to the last data byte. The CRC has to be attached to the data. Please find an example at the appendix of this document. For more details, please refer the publicly available Modbus documentation www.modbus.org.

Modbus communication

Digital outputs

| Output | Output Value | Read/Write | Manual override Communication | Read/Write* | Manual override Local | Read/Write* |
|------------------|--------------|------------|-----------------------------------|-------------|-----------------------------------|-------------|
| Digital Output 0 | Coil 30 | RW | Value Reg. 180 Enable Reg. 181 | RW | Value Reg. 200 Enable Reg. 201 | R |
| Digital Output 1 | Coil 31 | RW | Value Reg. 182 Enable Reg. 183 | RW | Value Reg. 202 Enable Reg. 203 | R |
| Digital Output 2 | Coil 32 | RW | Value Reg. 184 Enable Reg. 185 | RW | Value Reg. 204 Enable Reg. 205 | R |
| Digital Output 3 | Coil 33 | RW | Value Reg. 186 Enable Reg. 187 | RW | Value Reg. 206 Enable Reg. 207 | R |
| Digital Output 4 | Coil 34 | RW | Value Reg. 188 Enable Reg. 189 | RW | Value Reg. 208 Enable Reg. 209 | R |
| Digital Output 5 | Coil 35 | RW | Value Reg. 190 Enable Reg. 191 | RW | Value Reg. 210 Enable Reg. 211 | R |
| Digital Output 6 | Coil 36 | RW | Value Reg. 192 Enable Reg. 193 | RW | Value Reg. 212 Enable Reg. 213 | R |
| Digital Output 7 | Coil 37 | RW | Value Reg. 194 Enable Reg. 195 | RW | Value Reg. 214 Enable Reg. 215 | R |
| Digital Output 8 | Coil 38 | RW | Value Reg. 196 Enable Reg. 197 | RW | Value Reg. 216 Enable Reg. 217 | R |
| Digital Output 9 | Coil 39 | RW | Value Reg. 198 Enable Reg. 199 | RW | Value Reg. 218 Enable Reg. 219 | R |

^{*} Writable only if Modbus permission is set in the configuration, otherwise write has no effect

Normal operation: The outputs are set according the flag set by the communication.

Manual operation: The output are set according to the manual command, the communication flags are ignored.

Safe State: In case of a broken communication, a safe state value can be applied, see table Safe State Configuration.

Register format for manual override via Modbus (Reg. 180 ... 199):

Value Reg. Bit 0 Current output value

Enable Reg. Bit 14 1: output is driven in manual override by Modbus

Enable Reg. Bit 15 1: output is driven in manual override by local push buttons

Register format for local manual override (Reg. 200 ... 219):

Value Reg. Bit 0 Current output value

Enable Reg. Bit 15 1: output is driven in manual override by local push buttons

LED Configuration

| Digital Output 0 | Output L, Reg. 600 Output H, Reg. 601 | RW |
|------------------|--|----|
| Digital Output 1 | Output L, Reg. 602 Output H, Reg. 603 | RW |
| Digital Output 2 | Output L, Reg. 604 Output H, Reg. 605 | RW |
| Digital Output 3 | Output L, Reg. 606 Output H, Reg. 607 | RW |
| Digital Output 4 | Output L, Reg. 608 Output H, Reg. 609 | RW |
| Digital Output 5 | Output L, Reg. 610 Output H, Reg. 611 | RW |
| Digital Output 6 | Output L, Reg. 612 Output H, Reg. 613 | RW |
| Digital Output 7 | Output L, Reg. 614 Output H, Reg. 615 | RW |
| Digital Output 8 | Output L, Reg. 616 Output H, Reg. 617 | RW |
| Digital Output 9 | Output L, Reg. 618 Output H, Reg. 619 | RW |

Output L, Bit 0 ... 7 I/O state Low LED colour
Output L, Bit 8 ... 15 I/O state Low LED blink code
Output H, Bit 0 7 I/O state High LED colour

Output H, Bit 0 ... 7 I/O state High LED colour Output H, Bit 8 ... 15 I/O state High LED blink code

LED colour 0: Off

Register format:

1: Red 2: Green

3: Orange (red + green)

LED blink code 0: No blink

1: Slow blinking (0.5 flashes per second)
2: Fast blinking (2 flashes per second)

Factory default: Low: off, High: LED colour 2 (green), no blink

The LEDs can be configured individually depending on the I/O state in colour and blink code.

^{**}Writing to these registers has no effect. Used only if hardware permission is set in the configuration

Configuration for safe state and manual override

| Output | Safe State Enable | Read/Write | Safe State Value | Read/Write |
|---|--|------------|------------------|------------|
| Digital Output 0 | Coil 320 | RW | Coil 350 | RW |
| Digital Output 1 | Coil 321 | RW | Coil 351 | RW |
| Digital Output 2 | Coil 322 | RW | Coil 352 | RW |
| Digital Output 3 | Coil 323 | RW | Coil 353 | RW |
| Digital Output 4 | Coil 324 | RW | Coil 354 | RW |
| Digital Output 5 | Coil 325 | RW | Coil 355 | RW |
| Digital Output 6 | Coil 326 | RW | Coil 356 | RW |
| Digital Output 7 | Coil 327 | RW | Coil 357 | RW |
| Digital Output 8 | Coil 328 | RW | Coil 358 | RW |
| Digital Output 9 | Coil 329 | RW | Coil 359 | RW |
| | | | | |
| Communication safe state enable | default 0 (disabled) | | Coil 400 | RW |
| Power-On safe state enable defaul | t 0 (disabled) | | Coil 401 | RW |
| Power-On safe state timeout [ms], Valid values 1000 100,000,000, | default 30,000 | | Reg. 1180, 1181 | RW |
| Communication safe state timeout Valid values 1000 100,000,000, | | | Reg. 1182, 1183 | RW |
| Manual operation mode Bit 0: Disabled Bit 1: Remote control lim Bit 2: Local operation ena Bit 3: Remote control unl Bits can be combined to enable rei | abled, default 1 imited*, default 0 | | Register 1184 | RW |

^{*} If manual operation is locally activated at the module, the output value and manual state cannot be set/reset remotely

Manual operation mode:

- ▶ Disabled (0)
- ► Local operation only (4, Bit 2 set)
- ▶ Local operation enabled, remote limited (6, Bit 1 and 2 set), default
- ▶ Local and remote operation enabled (12, Bit 2 and 3 set)
- ► Remote operation only, local operation disabled (8, Bit 3 set)

The safe state enable flag and the safe state value are combined in the following way:

- Setting the enable coil to 0 keep the output value unchanged in case of safe state occurrence.
- Setting the enable coil to 1 writes the safe state value in case of safe state occurrence.

Device Information

| Firmware version (Decimal xyyzz, 10802 → 1.08.02) | Register 1200 | R |
|--|--------------------|---|
| Number of supported registers | Register 1202 | R |
| Number of supported flags | Register 1204 | R |
| Product type (ASCII String)* | Register 1210 1217 | R |
| Hardware version (Hex) | Register 1218 | R |
| Serial number (Hex) | Register 1222 1224 | R |
| Communication protocol (1: S-Bus Slave, 3: Modbus) | Register 1240 | R |
| Communication baud rate | Register 1242 | R |
| Communication auto baud enable (0:disabled, 1:enabled) | Register 1244 | R |
| Communication Mode | Register 1250 | R |
| 0: 8,E,1; 1: 8,O,1; 2: 8,N,2; 3: 8,N,1 | | |
| Communication module address | Register 1252 | R |

^{*} The eight registers contain the ASCII characters of the product type. E.g. for PCD1.A2000-A20: 1210...1217: 5043H | 4431H | 2E41H | 3230H | 3030H | 2D41H | 3230H | 0000H

CRC Generation Example

(Source: http://modbus.org/docs/PI_MBUS_300.pdf, the following content of this page is copied from the referenced document. In case of any questions, please check out the original source)

The function takes two arguments: unsigned char *puchMsg; A pointer to the message buffer containing binary data to be used for generating the CRC unsigned short usDataLen; The quantity of bytes in the message buffer. The function returns the CRC as a type unsigned short.

CRC Generation Function

```
unsigned short CRC16(puchMsg, usDataLen);
unsigned char *puchMsg :
                                                                                           /* message to calculate CRC upon */
                                                                                          /* quantity of bytes in message */
unsigned short usDataLen;
{
            unsigned char uchCRCHi = 0xFF;
                                                                                          /* high byte of CRC initialized */
                                                                                          /* low byte of CRC initialized */
            unsigned char uchCRCLo = 0xFF;
            unsigned uIndex;
                                                                                          /* will index into CRC lookup table */
            while (usDataLen--)
                                                                                          /* pass through message buffer */
                         uIndex = uchCRCHi ^ *puchMsgg++;
                                                                                          /* calculate the CRC */
                         uchCRCHi = uchCRCLo ^ auchCRCHi[uIndex];
                         uchCRCLo = auchCRCLo[uIndex];
             return (uchCRCHi << 8 | uchCRCLo);
High-Order Byte Table
/* Table of CRC values for high-order byte */
static unsigned char auchCRCHi[] = {
0x00, 0xC1, 0x81, 0x40, 0x01, 0xC0, 0x80, 0x41, 0x01, 0xC0, 0x80, 0x41, 0x00, 0xC1, 0x81, 0x40,
0x01, 0xC0, 0x80, 0x41, 0x00, 0xC1, 0x81, 0x40, 0x00, 0xC1, 0x81, 0x40, 0x01, 0xC0, 0x80, 0x41,
0x01, 0xC0, 0x80, 0x41, 0x00, 0xC1, 0x81, 0x40, 0xC1, 0x81, 0x40, 0x01, 0xC0, 0x80, 0x41,
0x00, 0xC1, 0x81, 0x40, 0x01, 0xC0, 0x80, 0x41, 0x01, 0xC0, 0x80, 0x41, 0x00, 0xC1, 0x81, 0x40,
0x01, 0xC0, 0x80, 0x41, 0x00, 0xC1, 0x81, 0x40, 0xC1, 0x81, 0x40, 0xC1, 0x81, 0x40, 0x01, 0xC0, 0x80, 0x41,
 0 \times 00, \ 0 \times C1, \ 0 \times 81, \ 0 \times 40, \ 0 \times 01, \ 0 \times C0, \ 0 \times 80, \ 0 \times 41, \ 0 \times C0, \ 0 \times 80, \ 0 \times 41, \ 0 \times 00, \ 0 \times C1, \ 0 \times 81, \ 0 \times 40, \ 0 \times C1, \ 0 \times
0x00, 0xC1, 0x81, 0x40, 0x01, 0xC0, 0x80, 0x41, 0x01, 0xC0, 0x80, 0x41, 0x00, 0xC1, 0x81, 0x40,
0x01, 0xC0, 0x80, 0x41, 0x00, 0xC1, 0x81, 0x40, 0x00, 0xC1, 0x81, 0x40, 0x01, 0xC0, 0x80, 0x41,
0x01, 0xC0, 0x80, 0x41, 0x00, 0xC1, 0x81, 0x40, 0x00, 0xC1, 0x81, 0x40, 0x01, 0xC0, 0x80, 0x41,
0x00, 0xC1, 0x81, 0x40, 0x01, 0xC0, 0x80, 0x41, 0x01, 0xC0, 0x80, 0x41, 0x00, 0xC1, 0x81, 0x40,
0x00, 0xC1, 0x81, 0x40, 0x01, 0xC0, 0x80, 0x41, 0x01, 0xC0, 0x80, 0x41, 0x00, 0xC1, 0x81, 0x40,
0x01, 0xC0, 0x80, 0x41, 0x00, 0xC1, 0x81, 0x40, 0x00, 0xC1, 0x81, 0x40, 0x01, 0xC0, 0x80, 0x41,
0x00, 0xC1, 0x81, 0x40, 0x01, 0xC0, 0x80, 0x41, 0x01, 0xC0, 0x80, 0x41, 0x00, 0xC1, 0x81, 0x40,
0x01, 0xC0, 0x80, 0x41, 0x00, 0xC1, 0x81, 0x40, 0x00, 0xC1, 0x81, 0x40, 0x01, 0xC0, 0x80, 0x41,
0x01, 0xC0, 0x80, 0x41, 0x00, 0xC1, 0x81, 0x40, 0x00, 0xC1, 0x81, 0x40, 0x01, 0xC0, 0x80, 0x41,
0x00, 0xC1, 0x81, 0x40, 0x01, 0xC0, 0x80, 0x41, 0x01, 0xC0, 0x80, 0x41, 0x00, 0xC1, 0x81, 0x40 );
Low-Order Byte Table
/* Table of CRC values for low-order byte */
static char auchCRCLo[] = {
0x00, 0xC0, 0xC1, 0x01, 0xC3, 0x03, 0x02, 0xC2, 0xC6, 0x06, 0x07, 0xC7, 0x05, 0xC5, 0xC4, 0x04,
0xCC, 0x0C, 0x0D, 0xCD, 0x0F, 0xCF, 0xCE, 0x0E, 0x0A, 0xCA, 0xCB, 0x0B, 0xCB, 0x0B, 0xCB,
0x08, 0x18, 0x19, 0x09, 0x18, 0x08, 0x0A, 0x1A, 0x1E, 0x0E, 0x0F, 0x1F, 0x0D, 0x1D, 0x1C, 0x0C,
0x14, 0xD4, 0xD5, 0x15, 0xD7, 0x15, 0xD6, 0xD6, 0xD2, 0x12, 0x13, 0xD3, 0x11, 0xD1, 0xD0, 0x10,
0xF0, 0x30, 0x31, 0xF1, 0x33, 0xF3, 0xF2, 0x32, 0x36, 0xF6, 0xF7, 0x37, 0xF5, 0x35, 0x34, 0xF4,
0x3C, 0xFC, 0xFD, 0x3D, 0xFF, 0x3F, 0x3E, 0xFE, 0xFA, 0x3A, 0x3B, 0xFB, 0x39, 0xF9, 0xF8, 0x38,
0x28, 0xE8, 0xE9, 0x29, 0xEB, 0x2B, 0x2A, 0xEA, 0xEE, 0x2E, 0x2F, 0xEF, 0x2D, 0xED, 0xEC, 0x2C,
0xE4, 0x24, 0x25, 0xE5, 0x27, 0xE7, 0xE6, 0x26, 0x22, 0xE2, 0xE3, 0x23, 0xE1, 0x21, 0x20, 0xE0,
0xA0, 0x60, 0x61, 0xA1, 0x63, 0xA3, 0xA2, 0x62, 0x66, 0xA6, 0xA7, 0x67, 0xA5, 0x65, 0x64, 0xA4,
0x6C, 0xAC, 0xAD, 0x6D, 0xAF, 0x6F, 0x6E, 0xAE, 0xAA, 0x6A, 0x6B, 0xAB, 0x69, 0xAB, 0x68,
0x78, 0x88, 0x89, 0x79, 0x88, 0x78, 0x78, 0x88, 0x8E, 0x7E, 0x8F, 0x7E, 0x8E, 0x7C,
0x84, 0x74, 0x75, 0x85, 0x77, 0x87, 0x86, 0x76, 0x72, 0x82, 0x83, 0x73, 0x81, 0x71, 0x70, 0x80,
0x50, 0x90, 0x91, 0x51, 0x93, 0x53, 0x52, 0x92, 0x96, 0x56, 0x57, 0x97, 0x55, 0x95, 0x94, 0x54,
0x9C, 0x5C, 0x5D, 0x9D, 0x5F, 0x9F, 0x9E, 0x5E, 0x5A, 0x9A, 0x9B, 0x5B, 0x9A, 0x9B, 0x5B, 0x5B, 0x5B, 0x5B, 0x9B,
0x88, 0x48, 0x49, 0x89, 0x4B, 0x8B, 0x8A, 0x4A, 0x4E, 0x8E, 0x8F, 0x4F, 0x8D, 0x4D, 0x4C, 0x8C,
0x44, 0x84, 0x85, 0x45, 0x87, 0x47, 0x46, 0x86, 0x82, 0x42, 0x43, 0x83, 0x41, 0x81, 0x80, 0x40 );
```



ATTENTION

These devices must only be installed by a professional electrician, otherwise there is the risk of fire or the risk of an electric shock.



WARNING

Product is not intended to be used in safety critical applications, using it in safety critical applications is unsafe.



WARNING - Safety

The unit is not suitable for the explosion-proof areas and the areas of use excluded in EN 61010 Part 1.



WARNING - Safety

Check compliance with nominal voltage before commissioning the device (see type label). Check that connection cables are free from damage and that, when wiring up the device, they are not connected to voltage.



NOTE

In order to avoid moisture in the device due to condensate build-up, acclimatise the device at room temperature for about half an hour before connecting.



CLEANING

The device can be cleaned in dead state with a dry cloth or cloth soaked in soap solution. Do not use caustic or solvent-containing substances for cleaning.



MAINTENANCE

These devices are maintenance-free. If damaged during transportation or storage, no repairs should be undertaken by the user.



GUARANTEE

Opening the module invalidates the guarantee.



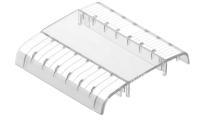
WEEE Directive 2012/19/EC Waste Electrical and Electronic Equipment directive

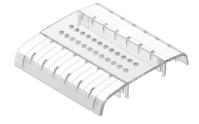
The product should not be disposed of with other household waste. Check for the nearest authorized collection centers or authorized recyclers. The correct disposal of end-of-life equipment will help prevent potential negative consequences for the environment and human health.



EAC Mark of Conformity for Machinery Exports to Russia, Kazakhstan or Belarus.







PCD1.K0206-005





Terminal set 32304321-003-S

Order details

| Туре | Short description | Description | Weight |
|----------------|---|--|--------|
| PCD1.A1000-A20 | E-Line S-Serie RIO 10DO | E-Line S-Serie digital output module Manual override operating level for all outputs Status LED for outputs Supply 24 VDC 10 digital outputs 24 VDC (1232 VDC/0.5 A) 1 interface RS-485 (S-Bus and Modbus) 1 USB service interface | 200 g |
| PCD1.K0206-005 | E-Line labelling set 5 × 6 HP* | E-Line cover and labelling set consisting of $5 \times$ covers (6 HP = 105 mm) and labelling sheet for mounting in the automation control cabinet | 365 g |
| PCD1.K0206-025 | E-Line labelling set 5 × 6 HP* with holes | E-Line cover and labelling set with holes consisting of 5 × covers (6 HP = 105 mm) with holes for manual override operating level and labelling sheet for mounting in the automation control cabinet | 365 g |
| 32304321-003-S | Terminal set | 6-pin terminal. Set of 6 terminal blocks | 40 g |

^{*} Horizontal pitch: 1 HP corresponds to 17.5 mm

Saia-Burgess Controls AG

Bahnhofstrasse 18 | 3280 Murten, Switzerland T +41 26 580 30 00 | F +41 26 580 34 99 www.saia-pcd.com